

CONTACT INFORMATION	CCDS 1326 665 Commonwealth Ave Boston, MA 02215 USA	arober@bu.edu <a href="https://arob5.github.io/">https://arob5.github.io/</a>
EDUCATION	<b>Boston University</b> , Boston, MA USA Ph.D., Computing and Data Sciences. <i>Advisors: Jonathan Huggins, Michael Dietze</i> Coursework as non-degree student	2021- present 2019 - 2020
	<b>Harvard Extension School</b> , Cambridge, MA USA Coursework as non-degree student	2018 - 2020
	<b>Tufts University</b> , Medford, MA USA B.S. Quantitative Economics	2014 - 2018
RESEARCH INTERESTS	I am broadly interested in uncertainty quantification, probabilistic modeling, and spatiotemporal forecasting, with the goal of developing new methodologies for environmental and ecological applications. I am currently working on applications to large-scale land surface models. I am passionate about bringing together researchers in the environmental, statistical, and computational sciences to address environmental challenges via an interdisciplinary approach.	
PROFESSIONAL EXPERIENCE	<b>Jet Propulsion Laboratory</b> , Pasadena, CA USA Intern, Uncertainty Quant. and Stat. Analysis	June 2024 - August 2024
	<b>Federal Reserve Bank of Boston</b> , Boston, MA USA Senior Research Assistant Research Assistant	July 2019 - June 2021 June 2018 - July 2019
	<b>World Bank</b> , Cambridge, MA USA Research Assistant	March - July 2018
	<b>Wiley Education Services</b> , Oak Brook, IL USA Decision Sciences Intern	June - Dec 2017
	<b>Patrivalor</b> , Madrid, ES Intern	Feb - May 2017
	<b>BW Research Partnership</b> , Boston, MA USA Intern	June 2016 - Feb 2017
HONORS AND AWARDS	<i>Summa Cum Laude</i> , Tufts University (2018)	

PROFESSIONAL SERVICE	<b>Mechanism Design for Social Good (MD4SG)</b> Co-organizer, Working Group on Environment Member, Working Group on Environment	Spring 2021-Spring 2023 Fall - Spring 2021
	<b>BU Chapter of the ASA (BUSCASA)</b> Vice President	Spring 2023 - Fall 2025
FELLOWSHIPS	<b>Boston University URBAN Fellowship</b> Previously funded through NSF	Spring 2024 - present
TEACHING	<b>Stochastic Methods for Algorithms</b> Teaching Fellow	Fall 2023, Fall 2025
EXTRA-CURRICULAR	Boston University Climbing Club Tufts Climate Action, Tufts University Tufts Energy Group, Tufts University	Fall 2021- present 2014 - 2015 2015

## PUBLICATIONS

1. N. Raoult, N. Douglas, N. MacBean, J. Kolassa, T. Quaife, **A.G. Roberts**, R.A. Fisher, I. Fer, C. Bacour, K. Dagon, L. Hawkins, N. Carvalhais, E. Cooper, M. Dietze, P. Gentine, T. Kaminski, D. Kennedy, H.M. Liddy, D. Moore, P. Peylin, E. Pinnington, B.M. Sanderson, M. Scholze, C. Seiler, T.L. Smallman, N. Vergopolan, T. Viskari, M. Williams, J. Zobitz (2024). Parameter Estimation in Land Surface Models: Challenges and Opportunities with Data Assimilation and Machine Learning. *Journal of Advances in Modeling Earth Systems*, 17, e2024MS004733. <https://doi.org/10.1029/2024MS004733>

## PREPRINTS

1. **Andrew G. Roberts**, Michael Dietze, and Jonathan H. Huggins. Propagating Surrogate Uncertainty in Bayesian Inverse Problems, *arXiv preprint*, 2026. <https://arxiv.org/abs/2601.03532>

## PEER REVIEW

1. Journal of Advances in Modeling Earth Systems (2025)
2. Conference on Neural Information Processing Systems (2024)

## POSTERS/TALKS

1. *Addressing Challenges in Scalable Ecosystem Modeling*, Presenter: Andrew Roberts. URBAN Biogeoscience and Environmental Health Symposium; Boston University; Boston, MA, May 2025
2. *Scalable Parameter Calibration for Expensive Ecosystem Models*, Presenter: Andrew Roberts, Collaborators: Michael Dietze, Jonathan Huggins. Ecological Forecasting Initiative (EFI2025), Virginia Tech; Blacksburg, VA, May 2025
3. *Bayesian Inversion with Probabilistic Surrogates: Posterior Approximation and Sequential Design* (Poster), Presenter: Andrew Roberts, Collaborators: Michael Dietze, Jonathan Huggins. Kernel Methods for Uncertainty Quantification and Experimental Design, Institute for Mathematical and Statistical Innovation (IMSI); Chicago, IL, April 2025.
4. *Gaussian process emulators for the solution of Bayesian inverse problems: applications to land surface modeling* (Talk), Presenter: Andrew Roberts, Collaborators: Michael Dietze, Jonathan Huggins. Uncertainty Quantification for Remote Sensing Inverse Problems; Jet Propulsion Laboratory, September 2024.
5. *Parameter Calibration and Uncertainty Quantification for Expensive Ecosystem Models* (Talk), Presenter: Andrew Roberts, Collaborators: Michael Dietze, Jonathan Huggins. 3rd New England Student Research Symposium in Statistics and Data Science; Boston University, April 2024.
6. *Active Learning for Posterior Approximation: Calibrating Expensive Ecosystem Models* (Poster), Presenter: Andrew Roberts, Collaborators: Michael Dietze, Jonathan Huggins. EnviBayes Workshop on Complex Environmental Data; Colorado State University, 2023.